# An Introduction to Prophet Inequalities 

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## Overview

(1) Introduction

- The Prophet Inequality Problem
- The Secretary Problem
(2) Generalizations and Constraints
- Selecting Multiple Values
- Online Contention Resolution Schemes
(3) Variations and Open Problems


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- The buyers have some private valuations $v_{1}, \ldots, v_{n}$ for the orange. How do we decide on what prices to offer?


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(3) Assume their valuations are arbitrary, but they arrive in random order.
$\Longrightarrow$ Secretary Problem*


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- We want to select the highest possible value, and compare against $X^{*}=\max _{1 \leq i \leq n} X_{i}$ on expectation.
- There exists an algorithm which selects a value $V$ such that $\mathbb{E}[V] \geq \frac{1}{2} \mathbb{E}\left[X^{*}\right]$, and no algorithm can achieve better competitive ratio [KS77].


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- Prophet inequalities provide guarantees for posted-price mechanisms in online auctions. Crucially, PPMs do not require bidding.


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(3) Strategy-Proof: There is no incentive for buyers to misreport, because we do not even ask them for a bid!


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## $\frac{1}{2}$ is Tight

- Consider two random variables $X_{1}$ and $X_{2}$, where $X_{1}=1$ deterministically, and $X_{2}=\frac{1}{\varepsilon}$ w.p. $\varepsilon$ and $X_{2}=0$ w.p. $1-\varepsilon$, for some small $\varepsilon>0$.
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- Every algorithm will receive value 1 on expectation, regardless of which element it picks.
- The expected value of the prophet is

$$
\mathbb{E}\left[X^{*}\right]=\frac{1}{\varepsilon} \cdot \varepsilon+1 \cdot(1-\varepsilon)=2-\varepsilon
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- Simple problem, with an elegant and striking solution.


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- Also, the decision whether to accept $v_{i}$ or not can only depend on $\left\{v_{1}, \ldots, v_{i}\right\}$. These imply that we should reject the first $r$ values, for some $r$, and accept the first $v_{i}$ where $i>r$ such that $v_{i}>\max _{1 \leq j \leq i-1} v_{i}$.


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- Let $r=\frac{n}{2}$ and $v_{2}^{*}$ denote the second-highest value. Then,
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- If that happens, we will select $v^{*}$. Therefore, for $r=\frac{n}{2}$,

$$
\operatorname{Pr}\left[v_{\text {sel }}=v^{*}\right] \geq \frac{1}{4}
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- In fact, the optimal policy is to set $r \approx \frac{n}{e}$. Then, one can show that $\operatorname{Pr}\left[v_{\text {sel }}=v^{*}\right] \geq \frac{1}{e}$, and this bound is tight [Lin61; Dyn63].


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- The bound of $\frac{1}{e}$ is tight in this case, although the tightness proof does not follow as easily.


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## A: "Adaptive-Threshold" Algorithm

For every $i \in[n]$, at step $i$, set a threshold $T_{i}$, based on $D_{1}, \ldots, D_{n}$ and $X_{1}, \ldots, X_{i-1}$, and accept every $X_{i} \geq T_{i}$ until we have selected $k$ values.

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- Since the realizations of the $X_{i}$ 's are independent, for an appropriately chosen $\delta$, one can show that the number of realizations that are at least $T$ are between $k-2 \delta$ and $k$, with high probability (Hoeffding bound).


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- For fixed realizations, let $S_{T}=\left\{i \in[n] \mid X_{i} \geq T\right\}$. Then

$$
\sum_{i \in S_{T}} X_{i}=\sum_{i \in S_{T}} T+\left(X_{i}-T\right)=T \cdot\left|S_{T}\right|+\sum_{i \in S_{T}}\left(X_{i}-T\right)
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- Then, it recursively chooses at most $\frac{k}{2}$ elements from the initial segment, and sets a threshold value equal to the $\frac{k}{2}$-th largest element of the initial segment.
- Finally, it chooses all elements of the final segment that meet this threshold until exhausting its $k$ allotted choices.


## Overview

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- We can generalize our problems even further by requiring the selected r.v.'s to be independent with respect to a constraint family $\mathcal{F}=([n], \mathcal{I})$. Here, we compare against $\mathbb{E}\left[\max _{S \in \mathcal{I}} \sum_{i \in S} X_{i}\right]$ in the prophet inequality setting.


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- [KW12] showed that there exists an (adaptive-threshold) algorithm for the Matroid Prophet Inequality Problem which matches the $\frac{1}{2}$-competitive ratio of the single-item case!
- In contrast, no constant-competitive algorithm is known for the Matroid Secretary Problem as of yet. The best known algorithm gives a $\mathrm{O}\left(\frac{1}{\log \log r}\right)$-competitive ratio, where $r$ is the rank of the matroid [Lac14; FSZ18].


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\begin{array}{ll}
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\text { s.t. } & \boldsymbol{y} \in \mathcal{P}_{\mathcal{I}} \quad(L P) \\
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where $\mathcal{P}_{\mathcal{I}}$ is a convex relaxation of $\mathcal{I}$.

- Solving (LP) yields a fractional point $\boldsymbol{x}$, which we want to round, subject to our constraints $\mathcal{F}$, but also in an online fashion.


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## Contention Resolution Scheme (informally) [CVZ11]

A $(b, c)$-balanced Contention Resolution Scheme (CRS) is a procedure which receives a point $\boldsymbol{x} \in b \cdot \mathcal{P}_{\mathcal{I}}$ as input and returns a set $S \in \mathcal{I}$ which contains every $i \in[n]$ with probability at least $c \cdot x_{i}$.

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- This guarantee yields a $b c$-approximation w.r.t. $O P T_{\mathrm{LP}}$, and thus also OPT.
- While CRSs are great, they are of no help for our problems, since we want to round the $x_{i}$ 's in an online fashion.


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- Essentially, an OCRSs that gives an $\alpha$-approximation w.r.t. $O P T_{L P}$ for a constraint $\mathcal{F}$, yields an equivalent $\alpha$-competitive algorithm for the prophet inequality problem w.r.t. $\mathcal{F}$.


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- They are nice because we can combine them to obtain OCRSs for more complicated constraints.
- Recently, prophet inequalities have been used to give optimal OCRSs for simple settings, implying the connection between the two is deeper.


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- Can we do better than $\frac{1}{2}$ ? In fact, yes! [Esf+15] showed that there exists a $1-\frac{1}{e}$-competitive algorithm, and recently, a $1-\frac{1}{e}+d$-competitive algorithm was discovered for some small constant $d>0$ [ACK17; CSZ18].


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- What if we knew that all random variables in the prophet inequality setting were i.i.d.? Clearly the optimal bound in this case is not worse than the prophet secretary problem.
- [Cor +17 ] showed that the optimal ratio is $\approx 0.7451$, and is actually tight.


## General Objectives

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- Other objective functions have been considered as well. In these settings, the objective is to select a set $S \in \mathcal{I}$ (for some constraint family $\mathcal{F}$ ) to maximize $\mathbb{E}[f(S)]$, and we compare against $\mathbb{E}\left[\max _{T \in \mathcal{I}} f(T)\right]$.


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- When $f$ is a submodular function, we can use OCRSs and obtain constant-competitive algorithms for the Submodular Prophet Inequality Problem [RS16]. More general functions (e.g. monotone subadditive) have been studied as well [Rub16; RS16].


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- Furthermore, when $f$ is a submodular function, [FZ18] showed that any $\alpha$-competitive algorithm for the Matroid Secretary Problem yields a O ( $\alpha$ )-competitive algorithm for the Submodular Matroid Secretary Problem.


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(3) What is the best constant for the Prophet Secretary Problem? and more...

## QUESTIONS ?



## Fixed-Threshold Algorithm for $k$-Prophet (Proof 1/2)

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- One can give a simple fixed-threshold algorithm for this setting, which achieves a $1-\mathrm{O}\left(\sqrt{\frac{\log k}{k}}\right)$-competitive ratio.
- Idea: Select a threshold $T$ such that the expected number of values $\geq T$ are $k-\delta$ for some $\delta$.
- Since the realizations of the $X_{i}$ 's are independent, for an appropriately chosen $\delta$, one can show that the number of realizations that are at least $T$ are between $k-2 \delta$ and $k$, with high probability (Hoeffding bound).
- For fixed realizations, let $S_{T}=\left\{i \in[n] \mid X_{i} \geq T\right\}$. Then

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\sum_{i \in S_{T}} X_{i}=\sum_{i \in S_{T}} T+\left(X_{i}-T\right)=T \cdot\left|S_{T}\right|+\sum_{i \in S_{T}}\left(X_{i}-T\right)
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- Since $\left|S_{T}\right| \geq k-2 \delta$, our revenue is at least $(k-2 \delta) T$.


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- Since $\left|S_{T}\right| \leq k$, we accepted every value that was at least $T$. Thus

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